

1 Article

# 2 Map Archive Mining: Visual-analytical Approaches 3 to Explore Large Historical Map Collections

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11 **Abstract:** Historical maps are unique sources of retrospective geographical information. Recently,  
12 several map archives containing map series covering large spatial and temporal extents have been  
13 systematically scanned and made available to the public. The geographical information contained  
14 in such data archives makes it possible to extend geospatial analysis retrospectively beyond the era  
15 of digital cartography. However, given the large data volumes of such archives (e.g., more than  
16 200,000 map sheets in the United States Geological Survey topographic map archive) and the low  
17 graphical quality of older, manually produced map sheets, the process to extract geographical  
18 information from these map archives needs to be automated to the highest degree possible. To  
19 understand the potential challenges (e.g., salient map characteristics and data quality variations) in  
20 automating large-scale information extraction tasks for map archives, it is useful to efficiently assess  
21 spatio-temporal coverage, approximate map content, and spatial accuracy of georeferenced map  
22 sheets at different map scales. Such preliminary analytical steps are often neglected or ignored in  
23 the map processing literature but represent critical phases that lay the foundation for any  
24 subsequent computational processes including recognition. Exemplified for the United States  
25 Geological Survey topographic map and the Sanborn fire insurance map archives, we demonstrate  
26 how such preliminary analyses can be systematically conducted using traditional analytical and  
27 cartographic techniques as well as visual-analytical data mining tools originating from machine  
28 learning and data science.

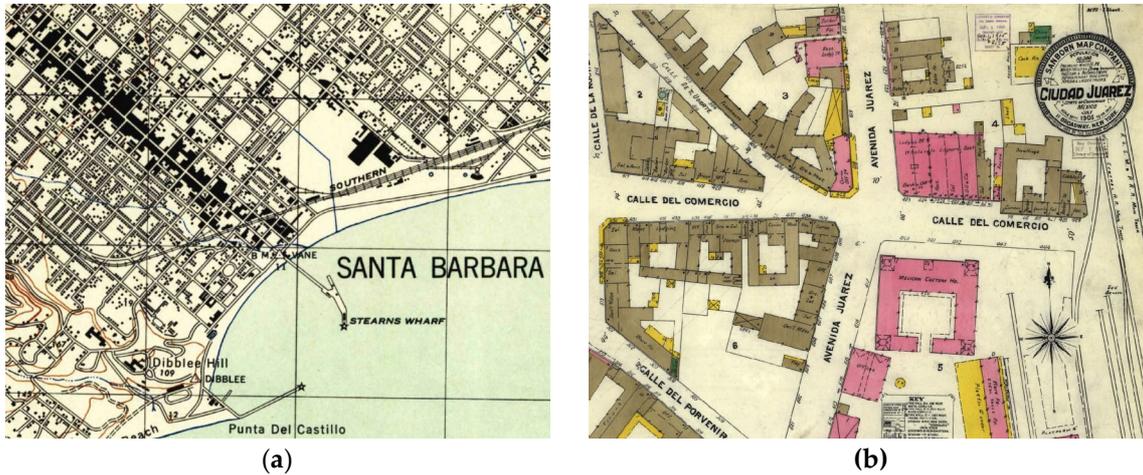
29 **Keywords:** map processing; retrospective landscape analysis; visual data mining, image information  
30 mining, low-level image descriptors, color moments, t-distributed stochastic neighborhood  
31 embedding, USGS topographic maps, Sanborn fire insurance maps  
32

## 33 1. Introduction

34 Historical maps contain valuable information about the Earth's surface in the past. This  
35 information can provide a detailed understanding of the evolution of the landscape as well as the  
36 interrelationships between human-made structures (e.g., transportation networks, settlements),  
37 vegetated land cover (e.g., forests, grasslands), terrain and hydrographic features (e.g., stream  
38 networks, water bodies). However, this spatial information is typically locked in scanned map images  
39 and needs to be extracted to get access to the geographic features of interest in machine readable data  
40 formats that can be imported into geospatial analysis environments.

41 Several efforts have recently been conducted in different countries to systematically scan,  
42 georeference, and publish entire series of topographic and other map documents. These  
43 developments include efforts at the United States Geological Survey (USGS), that scanned and  
44 georeferenced approx. 200,000 topographic maps published between 1884 and 2006 at different

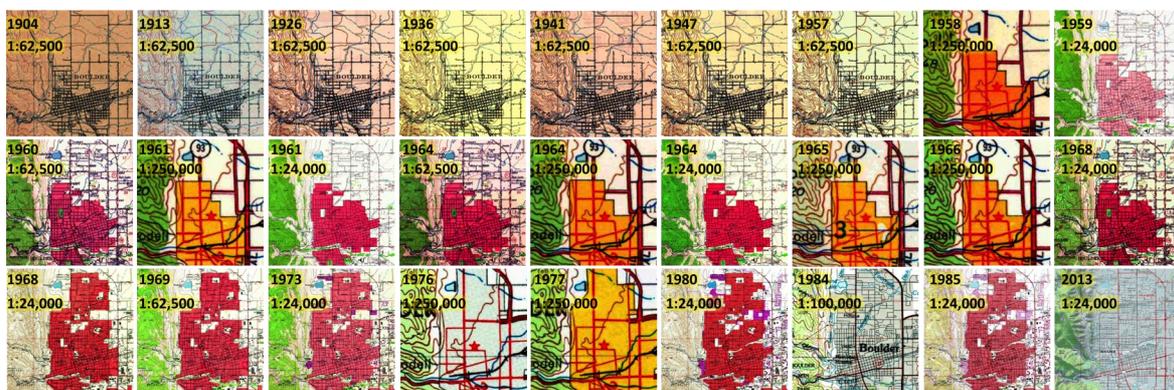
45 cartographic scales between 1:24,000 and 1:250,000 [1] and the Sanborn fire insurance map collection  
 46 maintained by the U.S. Library of Congress, that contains approximately 700,000 sheets of large-scale  
 47 maps of approximately 12,000 cities and towns in the U.S., Canada, Mexico, and Cuba, out of which  
 48 approximately 25,000 map sheets from over 3,000 cities have been published as scanned map  
 49 documents [2-4] (Figure 1). Furthermore, the National Library of Scotland scanned and georeferenced  
 50 more than 200,000 topographic map sheets and town plans for the United Kingdom dating back to  
 51 the 1840s and provides many of them as seamless georeferenced raster layers [5,6].  
 52



53 **Figure 1.** Examples of historical map documents: (a) Subsection of a USGS topographic map 1:31,680  
 54 of Santa Barbara (California, 1944) and (b) Sanborn fire insurance map from city center of Ciudad  
 55 Juárez (Mexico, 1905).

56 These developments, alongside with advances in information extraction and the processing,  
 57 storage and distribution of large data volumes, offer great potential for automated, large-scale  
 58 information extraction from historical cartographic document collections in order to preserve the  
 59 contained geographic information and make it accessible for geospatial analysis. Because of the large  
 60 amount of data contained in these map archives, information extraction has to achieve high degrees  
 61 of automation. For example, the USGS map archive has an approximate uncompressed data volume  
 62 of 50 terabytes, whereas the data volume of currently digitally available Sanborn fire insurance map  
 63 sheets can be estimated to approximately 3.7 terabytes.

64 This constitutes a challenging task given the high variability in the content and quality of map  
 65 sheets within an archive. Possible reasons for such variability are different conditions of the archived  
 66 analogue map documents, differences in the scan quality, as well as changes in the best practices in  
 67 cartographic design that may have resulted in different symbologies across map editions (Figure 2).  
 68



69 **Figure 2.** Available USGS topographic map sheets covering Boulder, Colorado (USA) from 1904 to  
 70 2013 at various map scales.  
 71

72 Typically, knowledge about the variability in content and quality of map archives are a priori  
73 not available, since such large amounts of data cannot be analyzed manually. However, such  
74 information is critical for a better understanding of the data sources and the design of efficient and  
75 effective information extraction methods. Thus, there is an urgent demand to develop a systematic  
76 approach to explore such digital map archives, efficiently, prior to the actual extraction process,  
77 similar to existing efforts for remote sensing data. In this contribution, we examine various techniques  
78 that could be used to build an image information mining system for digital cartographic document  
79 archives in combination with metadata analysis. These techniques aim to answer the following  
80 questions a potential user of such map archives may ask prior to the design and implementation of  
81 information extraction methods:

- 82
- 83 • **What is the spatial and temporal coverage of the map archive content and does it vary across**  
84 **different cartographic scales?** The user will need to know the potential extent, temporally and  
85 spatially, of the extracted data to understand benefit and value of the intended information  
86 extraction effort and for comparing different map archives.
- 87 • **How accurate is the georeference of maps contained in the archive? Does the accuracy vary in**  
88 **the spatio-temporal domain?** This constitutes a pressing question if ancillary geospatial data is  
89 used for the information extraction and certain degrees of spatial alignment with map features  
90 are required. For example, if it is possible to a priori identify map sheets likely to suffer from a  
91 high degree of positional inaccuracy, the user can exclude those map sheets from template or  
92 training data collection, and thus, reduce the amount of noise in the collected training data.
- 93 • **How much variability is there in the map content, regarding color, hue, contrast, and in the**  
94 **cartographic styles used to represent the symbol of interest?** This is a central question affecting  
95 the choice and design of a suitable recognition model. More powerful models or even different  
96 models for certain types of maps may be required if the representation of map content of interest  
97 varies heavily across the map archive. Furthermore, knowledge of variations in map content and  
98 similarity between individual map sheets is useful to optimize the design of training data  
99 sampling and to ensure the collection of representative and balanced training samples.

100

101 The set of methods described herein help determine the spatial-temporal coverage of a historical  
102 map archive, its content, existing variations in cartographic design, and to partially assess the spatial  
103 accuracy of the maps, which are all critical aspects for information extraction. These preprocessing  
104 stages are often neglected in published research that traditionally focuses on the extraction methods.  
105 The presented approaches range from pure metadata analysis to descriptor-based visual data mining  
106 techniques such as image information mining [7] used for the exploration of large remote sensing  
107 data archives. These methods are exemplified using the USGS topographic map archive and the  
108 Sanborn fire insurance map collection.

109 Chapter 2 gives an overview of related research. Chapter 3 introduces the data used in this work,  
110 and Chapter 4 describes the methods. Chapter 5 presents and discusses the results, and Chapter 6  
111 contains some concluding remarks and directions for future research.

## 112 2. Background and related research

### 113 2.1. Map processing

114 Map processing, or information extraction from digital map documents, is a branch of document  
115 analysis that focuses on the development of methods for the extraction and recognition of information  
116 in scanned cartographic documents. Map processing is an interdisciplinary field that combines  
117 elements of computer vision, pattern recognition, geomatics, cartography, and machine learning. The  
118 main goal of map processing is to “unlock” relevant information from scanned map documents to  
119 provide this information in digital, machine-readable geospatial data formats as a means to preserve  
120 the information digitally and facilitate the use of these data for analytical purposes [8].

121 Remotely sensed earth observation data from space and airborne sensors has been  
122 systematically acquired since the early 1970s and provides abundant information for the monitoring  
123 and assessment of geographic processes and how they interact over time. However, for the time  
124 periods prior to operational remote sensing technology, there is little (digital) information that can  
125 be used to document these processes. Map processing often focuses on the development of  
126 information extraction methods from map documents or engineering drawings created prior to the  
127 era of remote sensing and digital cartography, thus expanding the temporal extent for carrying out  
128 geographic analyses and landscape assessments to more than 100 years in many countries.

129 Information extraction from map documents includes the steps of *recognition* (i.e., identifying  
130 objects in a scanned map such as groups of contiguous pixels with homogeneous semantic meaning),  
131 and *extraction* i.e., transferring these objects into a machine-readable format (e.g., through  
132 vectorization). Extraction processes typically involve image segmentation techniques based on  
133 histogram analysis, color-space clustering, region growing or edge detection. Recognition in map  
134 processing is typically conducted using computer vision techniques including template matching  
135 techniques involving feature (e.g., shape) descriptors, cross-correlation measures, etc. Exemplary  
136 applications of map processing techniques include the extraction of buildings [9-11], road networks  
137 [12], contour lines [13], composite forest symbols [14], and the recognition of text from map  
138 documents [15,16]. Most approaches rely on handcrafted or manually collected templates of the  
139 cartographic symbol of interest and involve a significant level of user interaction, which impedes the  
140 application of such methods for large-scale information extraction tasks where high degrees of  
141 automation are necessary to process documents with high levels of variation in data quality.

## 142 2.2. Recent developments in map-based information extraction

143 The availability of abundant contemporary geospatial data for many regions of the world offers  
144 new opportunities to employ them as ancillary information to facilitate the extraction and analysis of  
145 geographic content from historical map documents. This includes the use of contemporary spatial  
146 data for georeferencing historical maps [17], assessing the presence of objects in historical maps across  
147 time [18], or the automated collection of template graphics for cartographic symbols of interest [19].

148 Most existing approaches for content extraction from historical maps still require a certain  
149 degree of user interaction to ensure acceptable extraction performance for individual map sheets, e.g.  
150 [20]. To overcome this persistent limitation, [21] and [22] propose the use of active learning and  
151 similar interactive concepts for more efficient recognition of cartographic symbols in historical maps,  
152 whereas [23] examine the usefulness of crowd-sourcing for the same purpose.

153 Moreover, the recent developments in deep machine learning in computer vision and image  
154 recognition have catalyzed the use of such techniques for geospatial information extraction from  
155 earth observation data [24-33]. This methodological development naturally projects into the idea of  
156 applying state-of-the-art machine learning techniques for information extraction from scanned  
157 cartographic documents, despite their fundamentally different characteristics compared to remotely  
158 sensed data. Key in both cases is the need for abundant and representative training data which  
159 requires automated sampling techniques. First attempts in this direction have used ancillary  
160 geospatial data for the collection of large amounts of training data in historical maps [34-37].

161 Alongside with the increasing availability of whole map archives as digital data, central  
162 challenges in map processing include the handling of the sheer data volume, the differences in  
163 cartographic scales and designs, changes in content, graphical quality and cartographic  
164 representations, the spatial and temporal coverage of the map sheets, and the spatial accuracy of the  
165 georeferenced map which dictates the degree of spatial agreement to contemporary geospatial  
166 ancillary data. While the previously described approaches represent promising directions towards  
167 higher levels of automation, they imply that the graphical characteristics of the map content to be  
168 extracted are known and that map scale and cartographic design remain approximately the same  
169 across the processed map documents.

170

### 171 2.3. Image information mining

172 The remote sensing community faces similar challenges. The steadily increasing amount of  
173 remotely sensed earth observation data requires effective mining techniques to explore the content  
174 of large remote sensing data archives. Therefore, visual data mining techniques have successfully  
175 been used to comprehensively visualize the content of such archives. Such image information mining  
176 systems facilitate discovery and retrieval using available metadata, and they make use of the  
177 similarity of the content of the individual datasets, or of patches of these [38-39], and guide  
178 exploratory analysis of large amounts of data to support subsequent development of information  
179 extraction methods. Such a system has for example been implemented for TerraSAR-X data [40], or  
180 for patches of Landsat ETM+ data and the UC Merced benchmark dataset [41]. These systems are  
181 based on spectral and textural descriptors precomputed at dataset or patch level that are then  
182 combined to multidimensional descriptors characterizing spectral-textural content of the datasets or  
183 patches. Other approaches include image segmentation methods to derive shape descriptors [42],  
184 integrate spatial relationships between images into the image information mining system [43], or  
185 make use of structural descriptors to characterize the change of geometric patterns over time across  
186 datasets within remote sensing data archives [44]. Comparison of these descriptors facilitates the  
187 retrieval of similar content across large archives. These approaches include methods for  
188 dimensionality reduction to visualize an entire data archive in a two or three-dimensional feature  
189 space based on content similarity.

190 Whereas in remote sensing data archives the spatio-temporal coverage of the data and their  
191 quality is relatively well-known based on the sensor characteristics (e.g., the time of operability,  
192 satellite orbit, revisiting frequency, knowledge about physical parameters affecting data quality), this  
193 may not always be the case for historical map archives, where metadata on spatial-temporal data  
194 coverage might not be available or available in semi-structured data formats only, impeding direct  
195 and systematic analysis.

## 196 3. Data

197 In this study, we analyzed map documents from the USGS map archive for the states of  
198 California (14,831 map sheets) and Colorado (6,964 map sheets). These map sheets were scanned by  
199 the USGS at a resolution of approximately 500 dpi (dots per inch) resulting in TIF files with an  
200 uncompressed data volume of more than 5.3 Terabyte for the two states under study. Whereas the  
201 authors were granted access to these data covering the two states at original scanning resolution,  
202 slightly downsampled versions of these map documents covering the whole U.S. can be publicly  
203 accessed at [45].

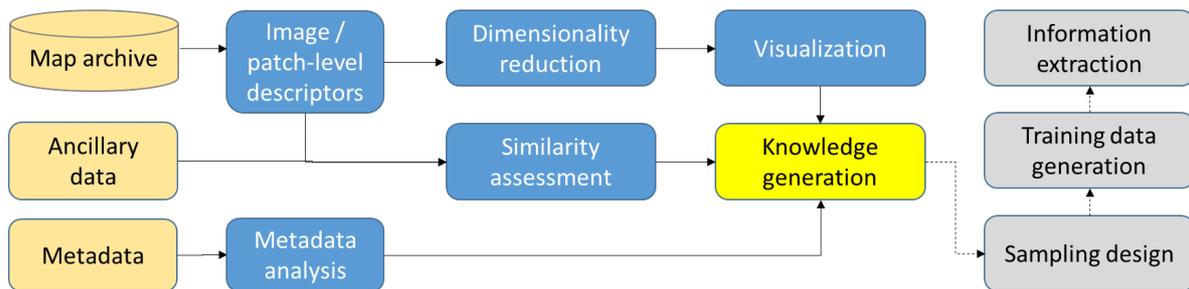
204 The delivered raw data was not georeferenced, but included metadata for the georeferencing  
205 process, i.e., coordinate pairs and error estimates of the ground control points (GCP) used for each  
206 individual map sheet allowing for batch georeferencing of the map sheets on the user side. In addition  
207 to that, corner coordinates of each map sheet are reported in the metadata allowing for the creation  
208 of spatial footprints (i.e., the USGS map quadrangle outlines) without georeferencing them. These  
209 metadata was available in a structured form in XML or CSV formats.

210 Furthermore, we used metadata of the Sanborn fire insurance map archive in this study,  
211 including the locations (i.e., geographic names), the reference years, and the number of map sheets  
212 available for each location, which is available as semi-structured HTML web content from the U.S.  
213 Library of Congress website [46].

## 214 4. Methods

215 We conducted *Metadata analysis* for the USGS topographic map archive exemplified for the  
216 states of California and Colorado based on structured metadata, as well as for the Sanborn fire  
217 insurance map archive in the United States based on semi-structured metadata. Next, we carried out  
218 *content-based image analysis* for the USGS topographic map archive covering the state of Colorado  
219 at different map scales, involving the use of image descriptors, dimensionality reduction and data

220 visualization methods, as well as a similarity assessment based on geospatial ancillary data. The  
 221 workflow diagram in Figure 3 shows how the proposed methods (in blue) based on given map data,  
 222 metadata and ancillary data (in beige) can be incorporated to generate knowledge useful for  
 223 subsequent information extraction procedures (in grey).  
 224



225

226 **Figure 3.** The methodology for metadata analysis of and content-based knowledge generation from  
 227 map archives to facilitate information extraction.

#### 228 4.1. Metadata analysis

##### 229 4.1.1. Spatio-temporal coverage analysis

230 Based on the *structured* metadata (i.e., map scale, reference year, corner coordinates, and GCP  
 231 coordinate pairs in XML and CSV data formats) available for the USGS map archive, we created  
 232 several aspatial visualizations (i.e., histograms and violin plots) illustrating the spatio-temporal  
 233 coverage of the map archive. Based on the spatial footprints of the map sheets, we computed  
 234 statistical measures such as the earliest reference year per map quadrangle and visualized them,  
 235 spatially, in order to reveal potential spatial patterns of the coverage in the spatio-temporal domain  
 236 (Section 5.1.1).

237 We retrieved the *semi-structured* metadata of the Sanborn map archive from HTML-based web  
 238 content to derive the geospatial location of each map location (i.e., town or city name, county, and  
 239 state) using web-based geocoding services to then visualize data availability and spatio-temporal  
 240 coverage of Sanborn map documents (Section 5.1.1).

##### 241 4.1.2. Assessing positional accuracy

242 Positional accuracy of scanned maps can be caused by several factors, such as paper map  
 243 distortions due to heat or humidity, the quality of surveying measurements on which the map  
 244 production is based, deviations from the local geodetic datum at data acquisition time, cartographic  
 245 generalization, and distortions introduced during the scanning and georeferencing process. While  
 246 most of these effects cannot be reconstructed or quantified in detail, metadata delivered with the  
 247 USGS topographic map archive contains information about the GCPs used for georeferencing the  
 248 scanned map documents that we used for a partial assessment of these distortions and resulting  
 249 positional inaccuracies.

250 The USGS topographic map quadrangle boundaries represent a graticule. For example, the  
 251 corner coordinates for quadrangles of scale 1:24,000 are spaced in a regular grid of 7.5'x7.5'.  
 252 Additionally, a finer graticule of 2.5'x2.5' is depicted in the maps. The intersections of this fine  
 253 graticule are used by the USGS to georeference the maps. Therefore, we collected the pixel  
 254 coordinates at those locations (i.e., the GCPs), and used the corresponding known world coordinates  
 255 of the graticule intersections to establish a second-order polynomial transformation based on least-  
 256 squares adjustment. We used this transformation to warp the scanned document into a georeferenced  
 257 raster dataset. We reported the GCP coordinate pairs in the metadata, as well as an error estimate per  
 258 GCP that provides information on the georeference accuracy in pixels. Based on these error estimates  
 259 given in pixel units and the spatial resolution of the georeferenced raster given in meters, we  
 260 calculated the root mean standard error (RMSE) reflecting the georeference accuracy in meters. We

261 appended these RMSE values as attributes to the map quadrangle polygons to visualize the  
262 georeference accuracy across the spatial-temporal domain.

263 Furthermore, we characterized the distortion introduced to the map by the warping process  
264 using displacement vectors computed between the known world coordinates of each GCP (i.e., the  
265 graticule intersections) and the world coordinates corresponding to the respective pixel coordinates  
266 after applying the second-order polynomial transformation. These displacement vectors reflected  
267 geometric distortions and positional inaccuracy in the original map (i.e., *prior* to the georeferencing  
268 process) but are also affected by additional distortions introduced during georeferencing or through  
269 scanner miscalibration.

270 Assuming that objects in the map are affected by the same degree of inaccuracy like the graticule  
271 intersections, the magnitudes of these displacement vectors make it possible to estimate the  
272 maximum displacements to be expected between objects in the map and their real-world counterparts  
273 that may not be corrected by the second order polynomial transformation. We visualized these  
274 displacement vectors to indicate the magnitude and direction of such distortions, and potentially  
275 identify anomalies (Section 5.1.2).

#### 276 4.2. Content-based image analysis

277 The presented metadata-based analysis provides valuable insights of spatial-temporal map  
278 availability, coverage, and spatial accuracy without analyzing the actual content of the map archives.  
279 However, it is important to inform the analyst about the degree of heterogeneity at the content-level.  
280 Therefore we computed low-level image descriptors (i.e., color moments) at multiple levels of  
281 granularity, i.e., for individual map sheets and for patches of maps. We then use these image  
282 descriptors as input to a dimensionality reduction method (i.e., t-distributed stochastic neighborhood  
283 embedding) in order to visualize the maps or map patches in a two or three dimensional space for  
284 effective visual map content assessment, and analytical assessment of their similarity.

##### 285 4.2.1. Low-level image descriptors

286 In order to obtain detailed knowledge about the content of map archives, we developed a  
287 framework based on low-level image descriptors computed for each map or map patches. We  
288 employed color-histogram based moments (i.e., mean, standard deviation, skewness and kurtosis,  
289 see [47]) computed for each image channel in the RGB color space. Mean and standard deviation  
290 characterize hue, brightness and contrast level of an image, skewness and kurtosis indicate the  
291 symmetry and flatness of the probability density of the color distributions, and thus reflect color  
292 spread and variability of an image. They are invariant to rotations, however, they do not take into  
293 account textural information contained in the image. We computed these four measures for each  
294 channel of an image and stacked them together to a 12-dimensional feature descriptor, at image or  
295 patch level. In the case of scanned map documents, such descriptors make it possible to retrieve maps  
296 or patches of maps of similar background color (depending on paper type and scan contrast level),  
297 and maps of similar dominant map content, such as waterbodies, urban areas, or forest cover. This  
298 similarity assessment was based on distances in the descriptor feature space and could also involve  
299 metadata (e.g., map reference year), or ancillary geospatial data, to assess map content similarity  
300 across or within different geographic settings.

##### 301 4.2.2. Dimensionality reduction

302 Furthermore, we employed approaches for dimensionality reduction such as t-distributed  
303 stochastic neighborhood embedding (t-SNE, [48]) to visualize the image data based on similarity in  
304 feature space. T-SNE allows for reducing the dimensionality of high-dimensional data, where the  
305 relative distances between the data points in the reduced feature space reflect the similarity of the  
306 data points in the original feature space. T-SNE is based on pair-wise similarities of data points, where  
307 the corresponding similarity measures in the target space are modelled by a Student-t-distribution  
308 [49]. The transformation of the data points into the target space of dimension 2 or 3 is conducted in

309 an iterative optimization process that aims to reflect local similarity and global clustering effects of  
310 the original space in the target space of a reduced dimensionality. This iterative process uses a  
311 gradient descent method to iteratively minimize a cost function and can be controlled by several user-  
312 defined parameters, such as the learning rate, perplexity, and maximum number of iterations. T-SNE  
313 is able to create visually appealing data representations in 2 or 3 dimensional spaces reflecting the  
314 inherent similarity and variability of the data, but may be prone to non-convergence effects resulting  
315 in meaningless visualizations if the chosen optimization parameters are not suitable for the data used.  
316 For the t-SNE transformations described in this work, we used a perplexity value of 30, a learning  
317 rate of 200, and a maximum number of 1,000 iterations, in order to yield visually satisfactory results,  
318 i.e., showing meaningful spatial patterns such as clusters. The application of this method to image-  
319 moments-based map descriptors facilitates the visual or quantitative identification of clusters of  
320 similar map sheets and provides a better understanding of the content of large map archives and  
321 their inherent variability. This kind of similarity assessment and metadata analysis is useful in  
322 generating knowledge which can be used to guide sampling designs to generate template or training  
323 data for supervised information extraction techniques.

#### 324 4.2.3. Multi-level content analysis

325 We computed image descriptors at different levels of spatial granularity, at the map level and  
326 map patch level.

327

328 **Content analysis at map level:** We analyzed the content of the entire map archive with respect  
329 to similarities between the individual map sheets by computing the image-moments based map  
330 descriptors and transforming them into a 3-dimensional space using t-SNE that can be visualized and  
331 interpreted intuitively.

332

333 **Content analysis at map patch level:** Map patches can be compared within a single map sheet,  
334 or across multiple map sheets. In order to assess the content *within map sheets*, we partitioned the  
335 map documents into tiles of a fixed size. We used the quadrangle boundaries based on corner  
336 coordinates delivered in the metadata to clip the map contents and removed non-geographic content  
337 in the map sheet edges. Then, we computed low-level descriptors based on color moments for each  
338 individual patch. If the patch size was chosen small enough, it appeared computationally feasible to  
339 use the raw (or down-sampled) patch data (e.g., a line vector of all pixel values in the patch) as a basis  
340 for t-SNE transformations. This could be useful if one desires to introduce a higher degree of  
341 spatiality and even directionality when assessing the similarity between the patches.

342 If variations of specific cartographic symbols *across map sheets* are of interest and have to be  
343 characterized, ancillary geospatial data can be employed to label the created map patches based on  
344 their spatial relationships to the ancillary data. For example, it may be important to assess the  
345 differences in cartographic representations of dense urban settlement areas across map sheets, in  
346 order to design a recognition model for urban settlement. To test such a situation, we employed  
347 building footprint data with built-year information and the respective spatio-temporal coverage to  
348 reconstruct settlement distributions in a given map reference year (see [50]). Based on these reference  
349 locations, we then computed building density surfaces for each map reference year and used  
350 appropriate thresholding to approximately delineate dense settlement areas for a given point in time.  
351 Based on spatial overlap between map patches and these dense reference settlement areas, we were  
352 able to identify map patches that are likely to contain urban area symbols across multiple maps. We  
353 the visualized these selected map patches in an integrated manner using t-SNE arrangements.

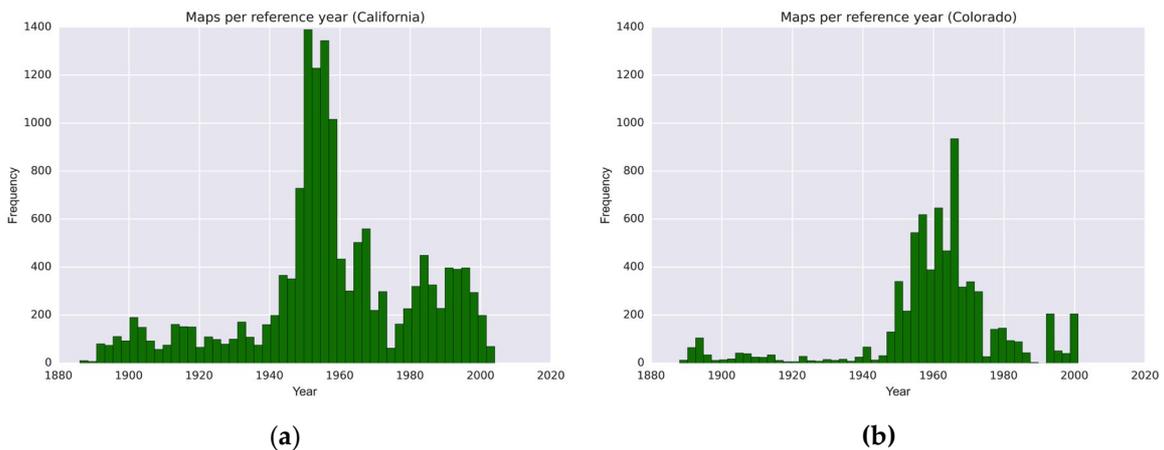
354

## 355 5. Results

### 356 5.1. Metadata analysis

#### 357 5.1.1. Metadata-based spatial-temporal coverage analysis

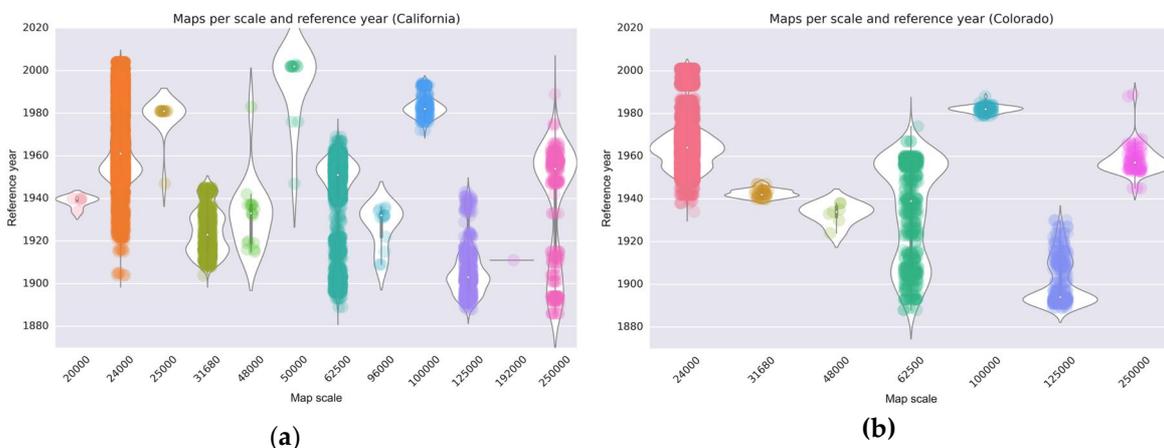
358 First, we analyzed the temporal coverage of the map archives. For the USGS map archive, we  
 359 created histograms based on the map reference year included in the accompanying metadata (Figure  
 360 4). It can be seen that the peak of map production in California was in the 1950s, and slightly later, in  
 361 the 1960s in Colorado.



362 **Figure 4.** Histograms of USGS topographic maps (all available map scales) by reference year, (a) in  
 363 California, and (b) in Colorado (USA).

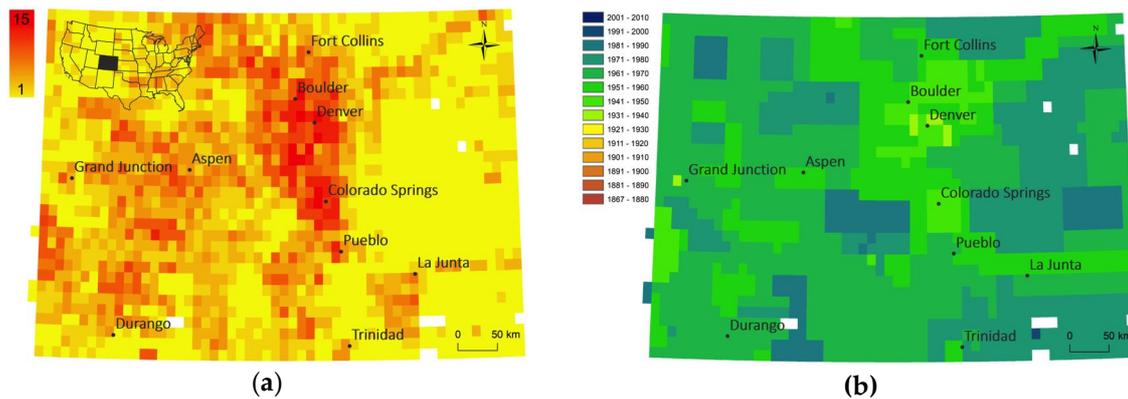
364 In addition to that, we assessed map production activity over time for different strata of map  
 365 scales shown for the states of California and Colorado (Figure 5). These plots show the temporal  
 366 distribution of published map editions (represented by the dots) and give an estimate of the  
 367 underlying probability density (represented by the white areas) that indicates the map production  
 368 intensity over time, separate and relative for each map scale. For example, this probability density  
 369 estimate reveals a peak of map production at scale 1:62,500 in Colorado (Figure 5b) around 1955  
 370 which is not visible in scatterplot alone. Such a representation helps to understand which time span  
 371 can be covered with maps of various scales and thus can be used to determine which products to  
 372 focus on for a particular purpose. This is important because maps of different scale contain different  
 373 levels of detail resulting from cartographic generalization.

374

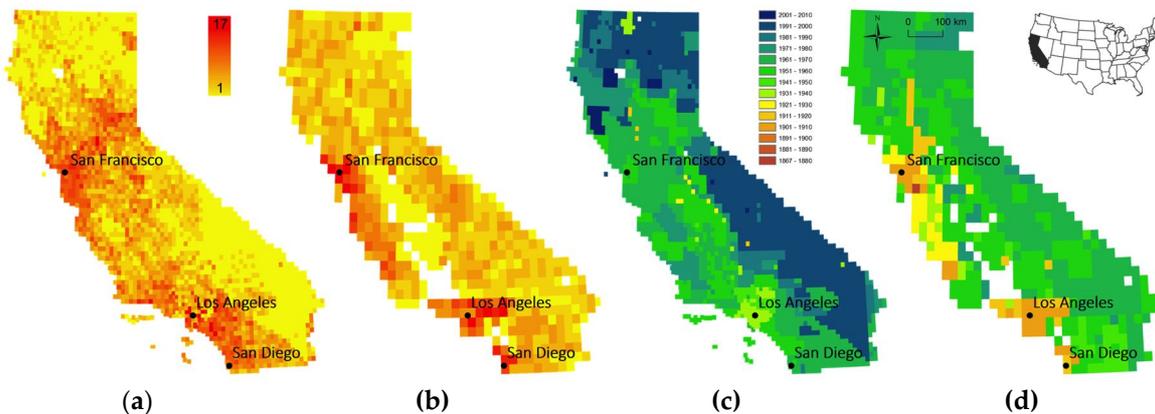


375 **Figure 5.** Produced USGS topographic maps per reference year and map scale (a) in California, and  
 376 (b) in Colorado (USA).

377 In order to assess the spatial variability of map availability in a map archive over time, we visualized  
 378 the number of map editions and the earliest reference year available for each location, in Figure 6 for  
 379 the state of Colorado (scale 1:24,000), and for the map scales 1:24,000 and 1:62,500 for the state of  
 380 California in Figure 7, respectively. Such representations are useful to identify regions that have been  
 381 mapped more intensively versus those for which temporal coverage is rather sparse. Furthermore, a  
 382 user is immediately informed about the earliest map sheets for a location of interest to understand  
 383 the maximum time period covered by these cartographic documents. Similar representations could  
 384 be created for the average number of years between editions or the time span covered by map editions  
 385 of a given map scale.



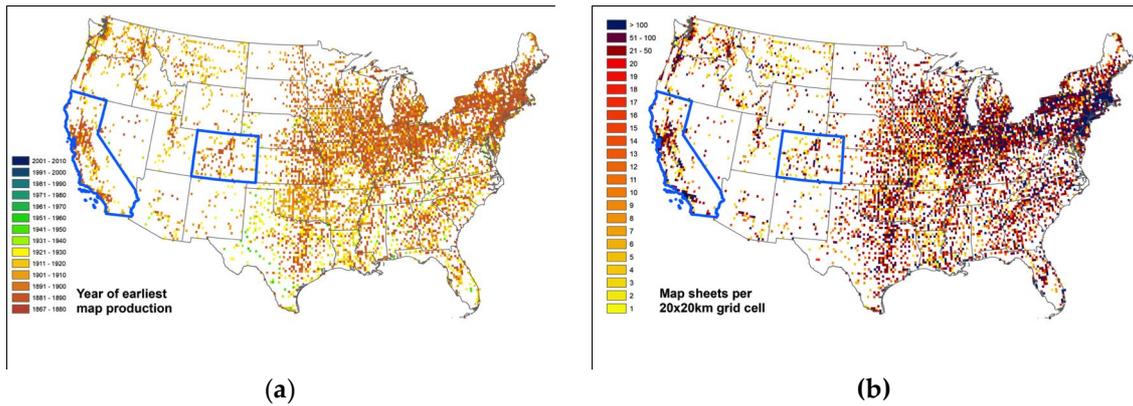
386 **Figure 6.** (a) Map edition counts and (b) earliest map production year per 1:24,000 map quadrangle  
 387 in the state of Colorado (USA) based on metadata analysis.



388  
 389 **Figure 7.** (a) Map edition counts per 1:24,000 map quadrangle, (b) map edition counts per 1:62,500  
 390 map quadrangle, (c) earliest map production year per 1:24,000 map quadrangle, and (d) earliest map  
 391 production year per 1:62,500 map quadrangle in the state of California (USA) based on metadata  
 392 analysis.

393 As a second example, we visualized the spatial-temporal coverage of the Sanborn fire insurance  
 394 map archive. Figure 8 shows, similar to the above examples, the year of the first map production and  
 395 the number of maps produced in total per location. The comparison of these visualizations for the  
 396 highlighted states of California and Colorado to the previously shown Figures 6 and 7 shows the  
 397 differences in spatio-temporal coverage between the two map archives, indicating a much sparser  
 398 spatial coverage of the Sanborn map archive, but extending further back in time than the USGS map  
 399 archive.

400

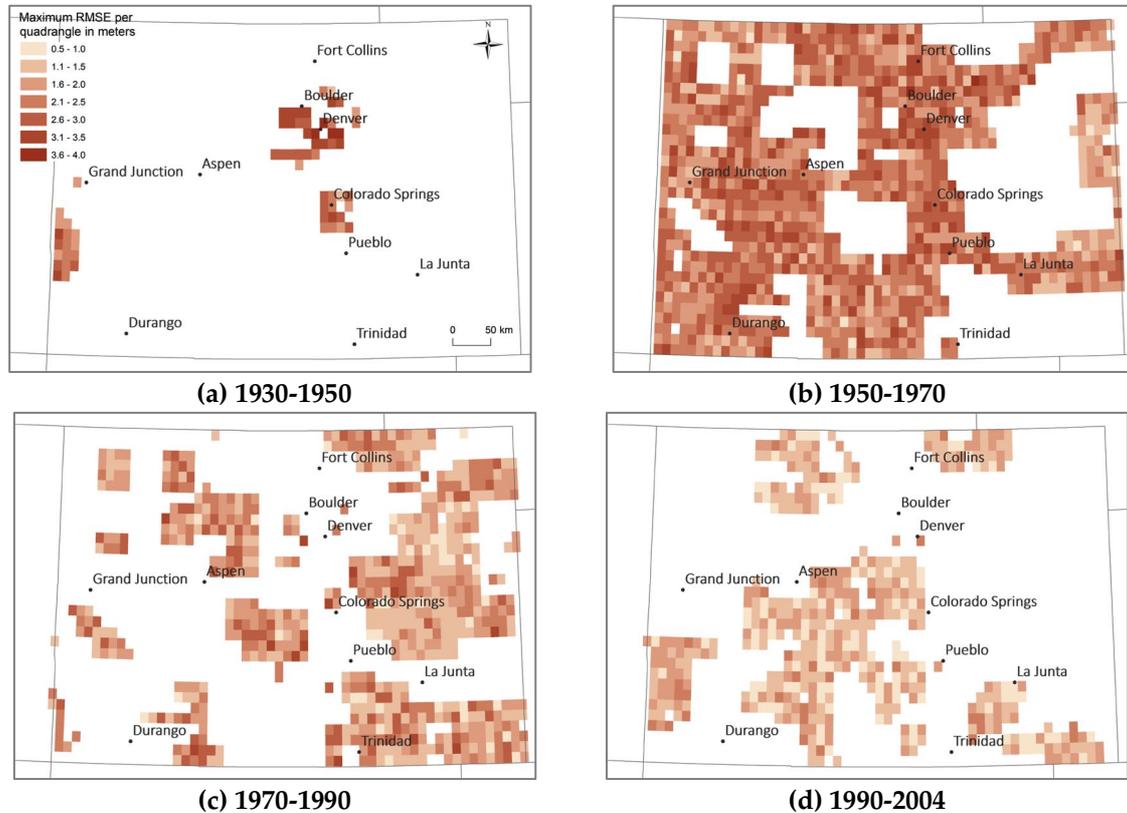


401 **Figure 8.** Sanborn fire insurance map archive coverage: (a) year of first map production per location  
 402 and (b) number of available map sheets per location, both aggregated to grid cells of 20km for efficient  
 403 visualization. Highlighted in blue the states of California and Colorado for comparison to the USGS  
 404 map coverage shown in the previous figures.

#### 405 5.1.2. Metadata-based spatial-temporal analysis of positional accuracy

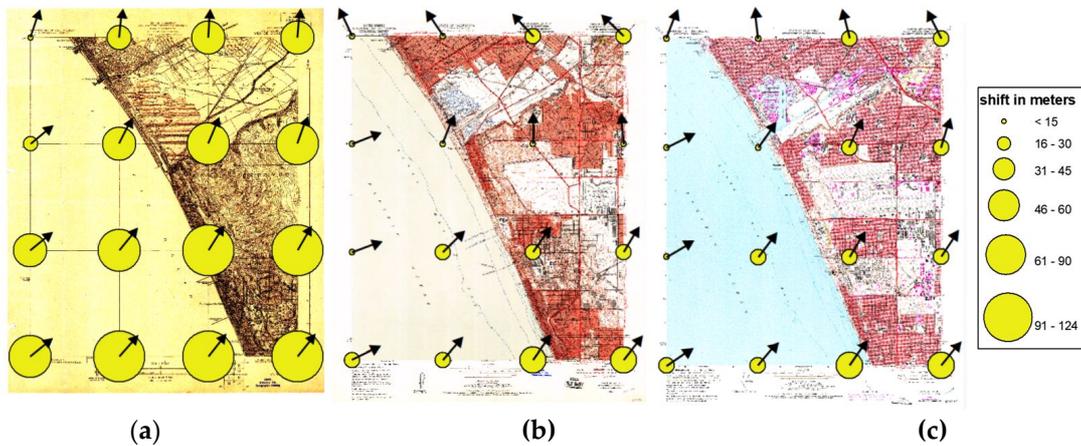
406 To illustrate the georeference accuracy for the USGS maps of scale 1:24,000 in the state of  
 407 Colorado (Figure 9) for different time periods, we visualized the maximum RMSE per quadrangle  
 408 and time period. Such temporally stratified representations are useful to examine whether the  
 409 georeference accuracy is constant over time. It can be seen that the earlier years in this example show  
 410 higher degrees of inaccuracy than more recent map sheets. This has important implications for the  
 411 user who is interested in using maps from different points in time that may exhibit different levels of  
 412 inaccuracy.

413



414 **Figure 9.** Spatio-temporal patterns of georeference accuracy of USGS topographic maps (1:24,000) in  
 415 the state of Colorado (USA), for maps produced between (a) 1930-1950, (b) 1950-1970, (c) 1970-1990,  
 416 and (d) 1990-2004.

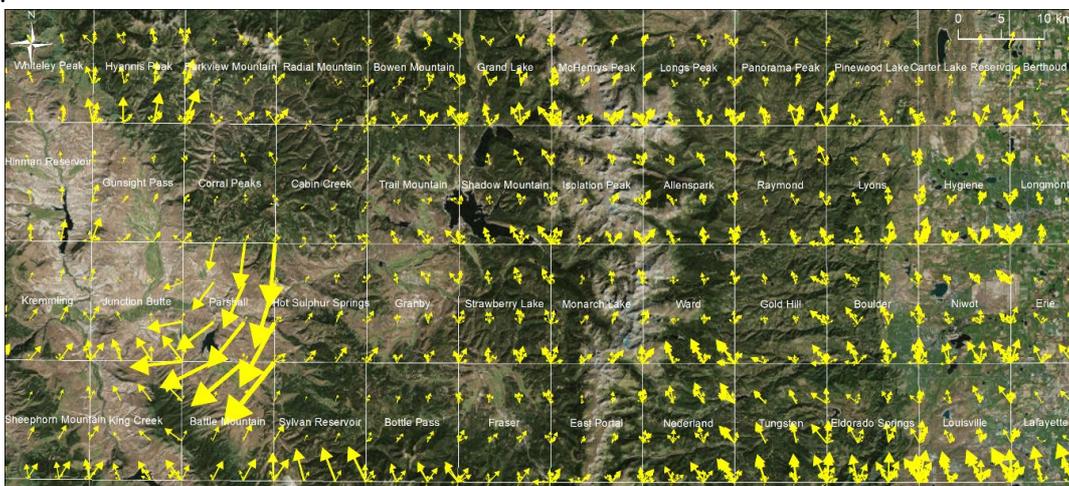
417 Figure 10 shows examples of these displacement vectors visualized for individual USGS map sheets at scale 1:24,000 from Venice (California) produced in 1923, 1957, and 1975. We represent the  
 418 magnitude of the local displacement by the dot area, whereas the arrow indicates the displacement  
 419 angle. This example shows similar patterns across the three maps, probably reflecting non-  
 420 independent distortions between the maps since earlier maps are typically used as base maps for  
 421 subsequent map editions, and some local variations due to inaccuracies introduced during  
 422 georeferencing of the individual map sheets.  
 423



424

425 **Figure 10.** Displacement vectors at GCP locations characterizing the distortions introduced during  
 426 the georeferencing of USGS topographic maps (scale 1:24,000) from Venice (California), produced in  
 427 (a) 1923, (b) in 1957, and (c) in 1975 (from left to right).

428 Additionally, we visualized these displacement vectors as vector fields across larger areas, to  
 429 identify regions, quadrangles, or individual maps of high or low positional reliability, respectively.  
 430 Figure 11 shows the vector field of relative displacements for USGS maps of scale 1:24,000 for a region  
 431 Northwest of Denver, Colorado. Notable are the large displacement vectors in the Parshall  
 432 quadrangle, indicating some anomalous map distortion, whereas the Cabin Creek quadrangle  
 433 (Northeast of Parshall) seems to have suffered from very slight distortions only. Such anomalous  
 434 distortions as detected in the Parshall quadrangle may indicate extreme distortions in the  
 435 corresponding paper map, or outliers in the GCP coordinates used for georeferencing. Multiple  
 436 arrows indicate the availability of multiple map editions in given quadrangles. Such visualizations  
 437 may inform map users about the heterogeneity in distortions applied to the map sheets during the  
 438 georeferencing process and may indicate different degrees of positional accuracy across a given study  
 439 area.



440

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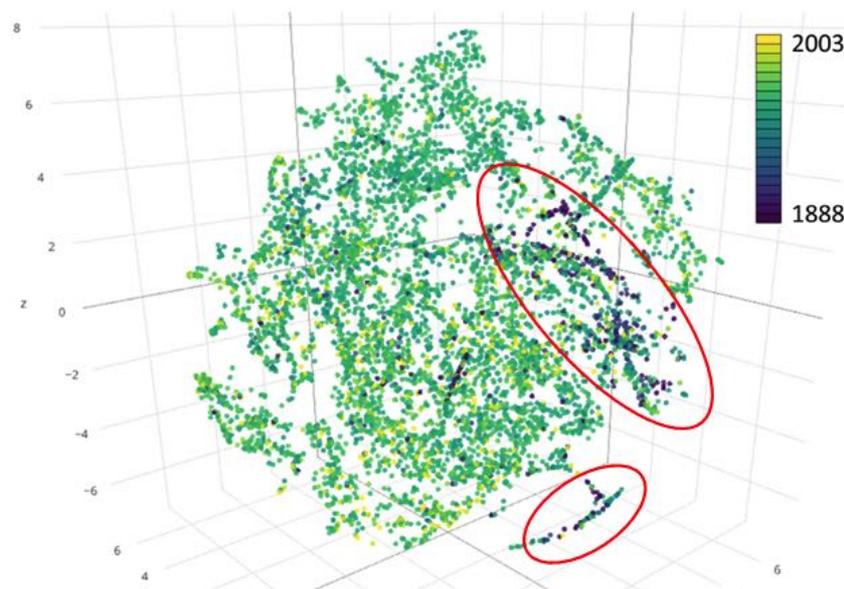
**Figure 11.** Displacement vector field at GCP locations over multiple USGS map quadrangles of scale 1:24,000, located North-west of Denver (Colorado), reflecting different types of distortions introduced to the map documents during the georeferencing process (Basemap source: [51]).

444 According to the USGS accuracy standards [52], a horizontal accuracy (i.e., RMSE) of <12.2  
 445 meters is required for maps at a scale of 1:24,000. Whereas the georeference accuracies visualized in  
 446 Figure 9 are all smaller or equal to 5 meters, we found that the magnitudes of the displacement vectors  
 447 shown in Figures 10 and 11 exceed the value of 12.2 meters, considerably. It is important to point out  
 448 that these displacement vectors may be caused by distortions in the paper map, by outliers in the  
 449 GCPs, or by differences in the spatial reference systems used in the original map and for  
 450 georeferencing. Thus, these displacement vectors do not represent the absolute horizontal map  
 451 accuracy alone, but rather serve as measures to characterize variability in the overall distortions  
 452 applied during the georeferencing across time and map sheets, and to identify anomalies such as  
 453 shown in Figure 11 where users should be careful with respect to further information extraction from  
 454 such map sheets.

## 455 5.2. Content-based analysis

### 456 5.2.1. Content-based analysis at map level

457 Figure 12 shows the map-level image descriptors transformed into a 3D feature space for the  
 458 6,964 USGS maps in the state of Colorado. We used the map reference year to color-code the points  
 459 representing individual map sheets. The highlighted clusters of dark blue points indicate  
 460 fundamentally different color characteristics of old maps in comparison to more recent maps  
 461 represented by points colored in green-yellow tones.



462

463 **Figure 12.** T-SNE visualization of the 6,964 USGS maps in the state of Colorado in a 3D feature space  
 464 based on 12-dimensional image descriptors obtained from channel-wise color moments.

465 In addition to color-coding the data points by the corresponding map reference year, we  
 466 transformed the 12-dimensional descriptors into a 2D feature space, and visualized them using  
 467 thumbnails of individual maps corresponding to each data point in Figure 12. This transformation  
 468 results in an integrated visual assessment of map archives containing large numbers of map sheets.  
 469 Figure 13 shows a t-SNE thumbnail visualization of a random sample (N=4,356) of the Colorado  
 470 USGS maps in a 2D feature space. We used nearest neighbor snapping to create a rectangular  
 471 visualization. This is a very effective way to visualize the variability in map contents, such as  
 472 dominating forest area proportions. It also illustrates the presence and abundance of different map  
 473 designs and base color use, e.g., high contrast and saturation levels in recent maps, compared to  
 474 yellow-tainted map sheets from the beginning of the 20<sup>th</sup> century centered at the bottom. The latter  
 475 corresponds to the cluster of historical maps located at the bottom of the point cloud in Figure 12.

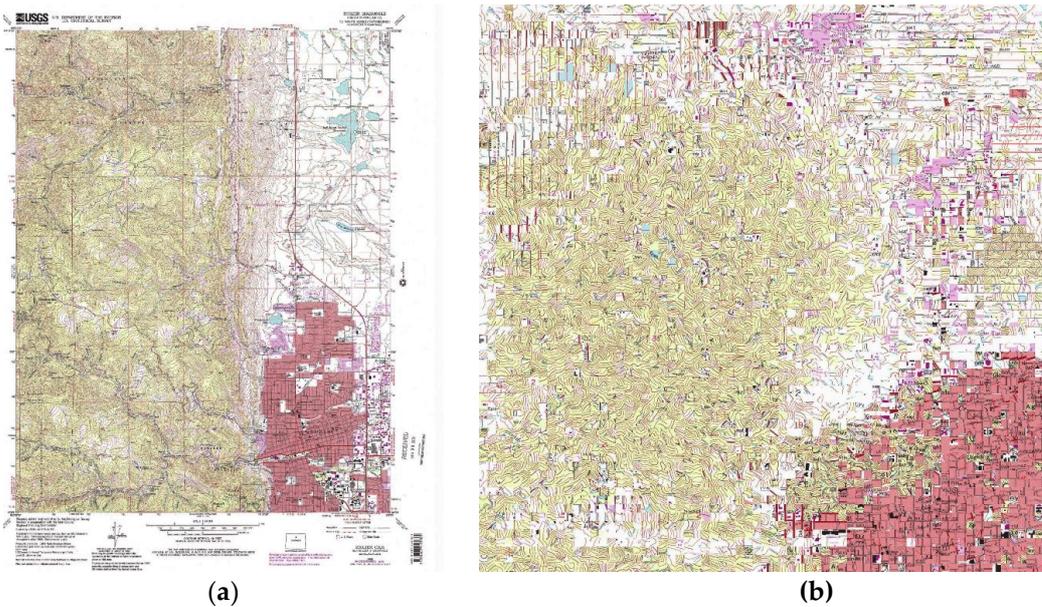


476

477 **Figure 13.** Thumbnail-based visualization of a subset of the USGS topographic maps in the state of  
478 Colorado (USA) based on a 2D transformation of the 12-dimensional image descriptor feature space  
479 using t-SNE.

#### 480 5.2.2. Content-based analysis at within-map patch level

481 We used the t-SNE transformation of patch-level descriptors to rearrange a map document in  
482 patches based on patch similarity, as shown for an example USGS map in Figure 14a. We partitioned  
483 the clipped map content in tiles of 100x100 pixels, down-sampled them by factor 4, and used the raw  
484 pixel values as input for the t-SNE transformation. This results in a 1,875-dimensional feature vector  
485 per patch. We then transformed these features into a 2D-space using t-SNE in order to create a  
486 similarity-based rearrangement of the map patches (Figure 14b). This rearrangement based on raw  
487 pixel values highlights for example the groups of linear objects of different dominant directions, such  
488 as road objects oriented in East-West and North-South direction (Figure 14b, upper right, and upper  
489 left, respectively), or clusters of patches that contain contour lines with diffuse directional  
490 characteristics (Figure 14b, center left) The incorporation of directionality may be useful to design  
491 sampling schemes that generate training data allowing for rotation-invariant feature learning.  
492



493 **Figure 14.** (a) USGS topographic map for Boulder, Colorado (1966), and (b) rearranged map patches  
 494 according to their similarity in a raw pixel value feature space using t-SNE.

### 495 5.2.3. Content-based analysis at cross-map patch level

496 Based on ancillary data indicating the presence of dense urban settlements (see Section 4.2.3), we  
 497 extracted patches that are likely to contain dense urban settlement symbols from map patches  
 498 collected across 50 USGS maps (1:24,000) in the states of Colorado and California, as shown in Figure  
 499 15. This arrangement illustrates nicely the different cartographic styles that are used to represent  
 500 dense urban settlements across time and map sheets, and provides valuable information useful for  
 501 the design of a recognition model. Additional samples could be collected at locations where no  
 502 ancillary data is available, and their content can be estimated based on descriptor similarity (i.e.,  
 503 patches of low Euclidean distance in the descriptor feature space) or using unsupervised or  
 504 supervised classification methods.

505



506

507 **Figure 15.** T-SNE arrangement of cross-map samples of patches likely to contain dense urban  
 508 settlement symbols.

## 509 6. Conclusions and Outlook

510 In this paper, we presented a set of methods for systematic information mining and content  
511 retrieval in large collections of cartographic documents, such as topographic map archives. These  
512 methods consist of pure metadata-based analyses, as well as content-based analyses using low-level  
513 image descriptors such as histogram-based color moments, and dimensionality reduction methods  
514 (i.e., t-SNE). We illustrate the proposed approach by exemplary analyses of the USGS topographic  
515 map archive and the Sanborn fire insurance map collection. Our approach can be used to explore and  
516 compare spatio-temporal coverage of these archives, the variability of positional accuracy, and  
517 differences in content of the map documents based on visual-analytical tools. These content-based  
518 map mining methods are inspired by image information mining systems implemented for remote  
519 sensing data archives.

520 More specifically, analysts aiming to develop information extraction methods from large map  
521 archives can benefit from the proposed methods as follows:

522

### 523 *Spatio-temporal coverage analysis:*

- 524 • Estimation of the spatio-temporal coverage of the extracted data
- 525 • Guidance for the design of the training data collection, to ensure the collection of balanced and  
526 representative training data across the spatio-temporal domain.

527

### 528 *Spatio-temporal analysis of spatial accuracy:*

- 529 • Estimating the spatial accuracy of the extracted data
- 530 • Excluding map sheets of potential low spatial accuracy to ensure high degrees of spatial  
531 alignment of map and ancillary data used for training data collection and thus, to reduce noise  
532 in the collected training data

533

### 534 *Content-based image analysis:*

- 535 • Assessing the variations in map content as a fundamental step in order to choose adequate  
536 information extraction methods capable of handling data of the given variability and to create  
537 representative training data accounting for such variations.

538

539 The presented methods have been tested and proven useful as preliminary steps to facilitate the  
540 design and implementation of information extraction methods from historical maps, e.g., regarding  
541 the choice of training areas and classification methods [34,35]. Further work will include the  
542 incorporation of suitable image descriptors accounting for textural information contained in map  
543 documents. Additionally, the benefit of indexing techniques based on image descriptors will be  
544 tested in a prototype map mining framework, facilitating the retrieval of similar map sheets in large  
545 map archives. Moreover, these efforts will contribute to the design of adequate sampling methods to  
546 generate large amounts of representative training data for large-scale information extraction methods  
547 from historical map archives based on deep-learning methods.

548 Such large-scale extraction of retrospective geographical information from historical map  
549 archives will contribute to create analysis-ready geospatial data for time periods prior to the era of  
550 digital cartography, and thus help to better understand the spatial-temporal evolution of human  
551 settlements, transportation infrastructure, forest coverage, or hydrographic features and their  
552 interactions with social and socio-economic phenomena over long periods of time. Such knowledge  
553 may be used to support and improve predictive land cover change models, and constitutes a valuable  
554 information base for decision making for planning or conservation purposes.

555 Similarly to web-based data storage and processing platforms for remote sensing data [53-55],  
556 adequate computational infrastructure will be required for effective processing of large volume map  
557 archives. The USGS data used in this study are accessed through a web storage service. We expect  
558 that in the near future additional map archives will be made available using similar web-based  
559 storage services that will facilitate the direct incorporation of the data into information extraction

560 processes (e.g., based on deep learning) implemented in cloud-computing platforms at reasonable  
561 computational performance and without previous manual and time-consuming data download.

562 The discussed content-based image analysis can be extended to most types of map archives as  
563 presented. The described metadata-based methods have the potential to be adapted to other existing  
564 map archives if metadata and georeference information is available in ways similar to the archives  
565 presented in this work. This study aims to raise awareness of the importance of a-priori knowledge  
566 of large spatial data archives before using the data for information extraction purposes and help to  
567 anticipate potential challenges involved. Such systematic mining approaches of relevant information  
568 about map archives help to inform and educate the user community on critical aspects of data  
569 availability, quality and spatio-temporal coverage.

570 In conclusion, this work demonstrates how state-of-the-art data analysis and information  
571 extraction methods are not only useful to handle and analyze large amounts of contemporary or real-  
572 time streaming data, but also provide computational infrastructure suitable for processing historical  
573 geospatial data.

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